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## PROGRAM

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### Program Elevator

```
do while (power == "on"){  
    do while (calls == 0){  
        updateCalls();  
    }  
  
    calculateNextFloor();  
    moveElevator()  
    in-&-Out();  
    updateCalls();  
  
    bringElevatorBack();  
}  
EDN
```

---

## VARIABLES

---

```
var calls = [0, 0, 0, 0, ....., 0, 0, 0];  
var currentfloor = 0;  
var nextFloor = 0;  
var floorsBetween = 0;  
var direction = "up";  
var power = "on";  
var upCallRequest = "no";  
var downCallRequest = "no";
```

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## FUNCTIONS

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```
function updateCalls(){

    if(upCallRequest == received) {
        var Request = floor wher this call came from;
        calls.UpRequest = 1;
    }

    if(downCallRequest == received) {
        var Request = floor wher this call came from;
        calls.UpRequest = 1
    }
}
```

```
function calculateNextFloor(){

    // we will keep the Call wit a FIFO system

    if (nextFloor > currentfloor){
        direction = " Up "
        floorsBtween = nextFloor - currentfloor;
    }

    if (nextFloor < currentfloor){
        direction = "Down"
        floorsBtween = currentfloor - nextFloor;
    }
}
```

```
function moveElevator(){

    if((nextFloor == currentFloor ){
        in-&-Out();
    }

    if(direction == " up " && floorsBtween < 3){
```

```
        goUpSlow(n);
        slowSpeed(n);
        stop(n);
    }
    if(direction == " up " && floorsBetween >= 3){
        goUpFullSpeed(n);
        slowSpeed(n);
        stop(n);
    }

    if(direction == "down" && floorsBetween < 3){
        goDownSlow(n);
        slowSpeed(n);
        stop(n);
    }
    if(direction == "down" && floorsBetween >= 3){
        goDownFullSpeed(n);
        slowSpeed(n);
        stop(n);
    }
}
```

```
function In-&-Out(){
    openElevatorDoor();
    deletethisFloorfromCalls();
    waith(13);
    obstaclesonDoorsCheck();
    closeElevatorDoor()
}
```

```
function wait(t){
    if (close door button is push): break;
    if (open door button is push): restart the wait time;
}
```

```
function stop(n){
```

```
var n = floorRequested;
checkifinbtweenfloors();
if (currentfloor == floorRequested){
    break;
else: adjust and then break;
}
}
```

```
function bringElevatorBack(){
    if (calls == 0){ // no requested call on hand
        if(currentfloor = 0){
            stop();
            break;
        }
        else{
            var Request = 0;
            calls.UpRequest = 1;
            moveElevator();
            break;
        }
    }
}
```

```
function obstaclesonDoorsCheck(){
    if (there is something between doors){
        openElevatorDoor();
        speakers = "Object obstructing doors";
        wait(3);
    }
}
```

```
function deletethisFloorfromCalls(){
    calls.currentfloor = 0;
}
```

```
function openElevatorDoor(){
    open elevator doors;
}

function closeElevatorDoor(){
    dowhile(doors are closing){
        obstaclesonDoorsCheck();
    }
}

function goUpFullSpeed(n){
    n = floorsBtween;
    move full speed "n" - 3 floors;
}

function goUpSlow(n){
    move slow speed reminder floors;
}

function goDownFullSpeed(n){
    n = floorsBtween;
    move full speed "n" + 3 floors;
}

function goDownSlow(n){
    move slow speed reminder floors;
}

function slowSpeed(){
    went entering the final flour:
        comence deceleration to speed "0";
}

function checkifinbtweenfloors(){
```

```
check building marks
if(BuildingMark = 0){
    break;
}
else{
    adjust towars "0";
}
}
```